

$$\gamma(t) = (\cos^3 t, \sin^3 t, 0)$$

\mathbb{R}^3

$$K = \frac{\|\gamma'' \times \gamma'\|}{\|\gamma'\|^3}$$

$$\gamma'(t) = (-3\cos^2 t \sin t, 3\sin^2 t \cos t, 0) \quad \|\gamma'\| = 3|\sin t \cos t|$$

$$\gamma''(t) = (6\cos t \sin^2 t - 3\cos^3 t, 6\sin t \cos^2 t - 3\sin^3 t, 0)$$

$$\gamma'' \times \gamma' = \begin{vmatrix} -i & j & k \\ 6\cos t \sin^2 t - 3\cos^3 t & 6\sin t \cos^2 t - 3\sin^3 t & 0 \\ -3\cos^2 t \sin t & 3\sin^2 t \cos t & 0 \end{vmatrix}$$

$$= (18\cos^2 t \sin^4 t - 9\cos^4 t \sin^2 t) - (-18\cos^4 t \sin^2 t + 9\cos^2 t \sin^4 t)$$

$$= 18\cos^2 t \sin^2 t - 9\cos^2 t \sin^2 t$$

$$= 9\cos^2 t \sin^2 t$$

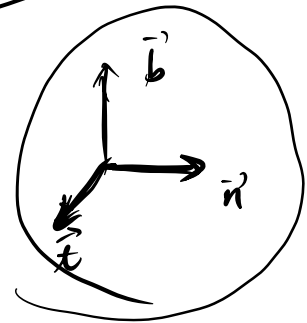
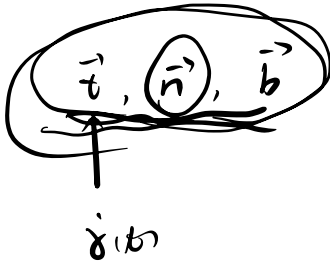
$$= (0, 0, 9\cos^2 t \sin^2 t)$$

$$k = \frac{9 \omega^2 \sin^2 \theta}{|3 \sin \omega t|^3} = \frac{1}{3 |\sin \omega t|}$$

torsion

$k \neq 0$

$$\tau = \frac{(\dot{\gamma} \times \ddot{\gamma}) \cdot \ddot{\gamma}}{\|\dot{\gamma} \times \ddot{\gamma}\|^2} = (\dot{\gamma}, \ddot{\gamma}, \ddot{\gamma})$$



$$\vec{n} = \frac{1}{k} \dot{\vec{t}}$$

$$\vec{b} = \vec{t} \times \vec{n}$$

$$\dot{\vec{t}} = k \vec{n}$$

$$\vec{b} = -\vec{t} \times \vec{n}$$

torsion

$$\dot{\vec{n}} = \lambda \vec{t} + \mu \vec{n} + \nu \vec{b}$$

$$\Rightarrow \begin{cases} \vec{t} \cdot \dot{\vec{n}} = \lambda \\ \vec{n} \cdot \dot{\vec{n}} = \mu \\ \vec{b} \cdot \dot{\vec{n}} = \nu \end{cases} \Rightarrow \mu = 0$$

$$\|\vec{t}\| = 1$$

$$\|\dot{\vec{t}}\| = k$$

$$\vec{n} = \frac{1}{k} \dot{\vec{t}}$$

$$\nu = (\vec{n} \cdot \dot{\vec{t}})' = \dot{\vec{n}} \cdot \vec{t} + \frac{\vec{n} \cdot \dot{\vec{t}}}{\frac{1}{k} \|\dot{\vec{t}}\|^2} = \lambda + k$$

$$\vec{n} \cdot \dot{\vec{t}} = k$$

$$\Rightarrow \lambda = -k$$

$$\begin{aligned} 0 = (\mathbf{b} \cdot \mathbf{n})' &= \dot{\mathbf{b}} \cdot \mathbf{n} + \mathbf{b} \cdot \dot{\mathbf{n}} \\ &= -\tau + \nu \end{aligned}$$

$$\Rightarrow \nu = \tau.$$

$$\Rightarrow \begin{aligned} \dot{t} &= \kappa n \\ \dot{n} &= -\kappa t + 0 \cdot n + \tau b \\ \dot{b} &= -\tau n \end{aligned}$$

$$\Rightarrow \frac{d}{ds} \begin{pmatrix} t \\ n \\ b \end{pmatrix} = \begin{pmatrix} 0 & \kappa & 0 \\ -\kappa & 0 & \tau \\ 0 & -\tau & 0 \end{pmatrix} \begin{pmatrix} t \\ n \\ b \end{pmatrix}$$

differential equation.

$$\mathbf{b} = -\tau \mathbf{n}$$

Frenet-Serret equation

Prop. Let γ be a unit speed curve in \mathbb{R}^3 , $\kappa = \text{const.}$, $\tau = 0$.

Then γ is a (part of) circle.

pf. $\tau = 0 \Rightarrow \mathbf{b} = \text{const.}$

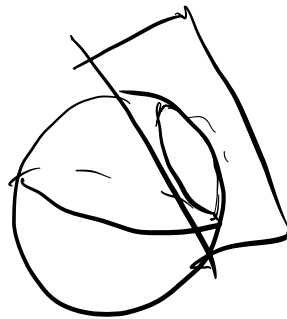
$$\frac{d}{ds} \left(\gamma + \frac{1}{\kappa} \mathbf{n} \right) = \mathbf{t} + \frac{1}{\kappa} \dot{\mathbf{n}} = \mathbf{t} + \frac{1}{\kappa} (-\kappa \mathbf{t}) = \mathbf{0}$$

$$\underline{\underline{n}} = -\underbrace{(kb)} + \underbrace{(Tb)} = \underbrace{(kt)}$$

$$\underline{\underline{\delta}} + \underbrace{\left(\frac{1}{k}n\right)} = \underline{\underline{a}}$$

$$\Rightarrow \underline{\underline{\|\delta - a\|}} = \underbrace{\left(\frac{1}{k}\right)}$$

$$\Rightarrow \underline{\underline{(\checkmark)}}$$



Thm 2.3.6. $k > 0$ (T) smooth. $\exists!$ δ .

§3 Surfaces in 3-d

§3.1 What is a surface?



$$\underline{\underline{a(u,v)}} = \underline{\underline{a + (up + vq)}}$$

$$\underline{\underline{a: \mathbb{R}^2 \rightarrow \mathbb{R}^3}}$$

Def 3.1.1 A surface patch is a smooth injective map

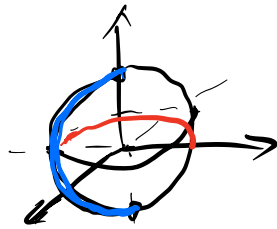
(a) $U \rightarrow \mathbb{R}^3$, where $(U) \subset \mathbb{R}^2$ is an open set.

open set: $\forall (x_0) \in U, \exists \delta_{x_0}, s.t. \forall x: \|x - x_0\| < \delta \Rightarrow x \in U.$

Exam

$$\alpha(u, \varphi) = (\cos u \cos \varphi, \cos u \sin \varphi, \sin u)$$

$$(0 < \varphi < 2\pi, -\frac{\pi}{2} < u < \frac{\pi}{2})$$



$$\tilde{\alpha}(u, \varphi) = (-\cos u \cos \varphi, -\sin u, -\cos u \sin \varphi)$$

Def 4.1: A surface patch $\tilde{\alpha}: \tilde{U} \rightarrow \mathbb{R}^3$ is a reparametrization of a surface patch $\alpha: U \rightarrow \mathbb{R}^3$ if there exists a bijective $\Phi: U \rightarrow \tilde{U}$, is smooth, and $\Phi^{-1}: \tilde{U} \rightarrow U$ is also smooth.

(diffeomorphism): $\tilde{\alpha}(\Phi(u, v)) = \alpha(u, v), \forall (u, v) \in U.$

$$(\tilde{u}, \tilde{v}) = \Phi(u, v), \quad (u, v) = \Phi^{-1}(\tilde{u}, \tilde{v})$$

$$\underline{J(\Phi)} = \begin{pmatrix} \frac{\partial \tilde{u}}{\partial u} & \frac{\partial \tilde{u}}{\partial v} \\ \frac{\partial \tilde{v}}{\partial u} & \frac{\partial \tilde{v}}{\partial v} \end{pmatrix}, \quad \underline{J(\Phi^{-1})} = \begin{pmatrix} \frac{\partial u}{\partial \tilde{u}} & \frac{\partial u}{\partial \tilde{v}} \\ \frac{\partial v}{\partial \tilde{u}} & \frac{\partial v}{\partial \tilde{v}} \end{pmatrix}$$

$$\underline{J(\Phi) \cdot J(\Phi^{-1}) = \text{id.}}$$

$$\underline{\|\dot{\gamma}\| \neq 0}$$

Def 0.2.1 Let $\alpha: U \rightarrow \mathbb{R}^3$ be smooth surface patch. let $S \subset \mathbb{R}^3$ be its image, let $p \in S$. The Tangent space to S at p is the set of all tangent vectors at p to smooth curves through p .

TpS



$$\alpha(u, v)$$

$$\underline{\alpha_u = \frac{\partial \alpha}{\partial u}}$$

Prop 0.2.2 the tangent space to S at p is the subvector space of \mathbb{R}^3 spanned by α_u and α_v .

Pf.

$$\underline{\gamma(t) = \alpha(u(t), v(t))}$$

chain rule

$$\underline{\dot{\gamma}(t) = \alpha_u \cdot \left(\frac{du}{dt}\right) + \alpha_v \cdot \left(\frac{dv}{dt}\right)}$$

$$= \underline{a\alpha_u + b\alpha_v} \in \underline{\langle \alpha_u, \alpha_v \rangle}$$

$$\underline{\alpha_u, \alpha_v \in T_p S.}$$

$$\Leftrightarrow \underline{T_p S = \langle \alpha_u, \alpha_v \rangle}$$

a_u, a_v linearly independent

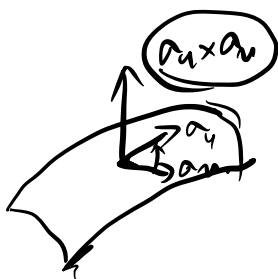
$\in \mathbb{R}^3$

$$a_u \times a_v \neq 0$$

$$i \neq 0$$

$$a_u \neq 0, a_v \neq 0$$

Def 4.2.3. A surface $\alpha: U \rightarrow \mathbb{R}^3$ is regular if $a_u \times a_v \neq 0$ for $(u, v) \in U$.



Def

$$\vec{N} =$$

$$\frac{a_u \times a_v}{\|a_u \times a_v\|}$$

normal vector of S .

$$t = a_u + b a_v$$

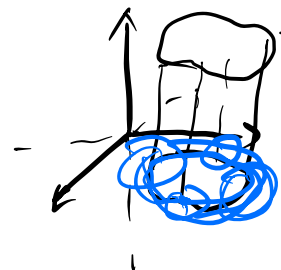
$$t \cdot \vec{N} = a a_u \cdot \vec{N} + b a_v \cdot \vec{N} = 0, \quad \forall t \in T_p S.$$

Exam. (generalized) cylinder

$$\alpha(u, v) = (f(u), g(u), v)$$

$$a_u = (f', g', 0)$$

$$a_v = (0, 0, 1)$$



$$a_u \times a_v = \begin{vmatrix} i & j & k \\ f' & g' & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

manifold 流形 = $(g', -f', 0) \neq 0$

$$\Leftrightarrow \underbrace{(g')^2 + (f')^2} \neq 0$$

$$\gamma(t) = (f(t), g(t))$$

$$f = \cos u, \quad g = \sin u$$

$$\Leftrightarrow \underline{\delta(t) \neq 0}$$

If $\gamma(t)$ is regular, then $\sigma(u, v)$ is also regular.

Exam (generalized) wre

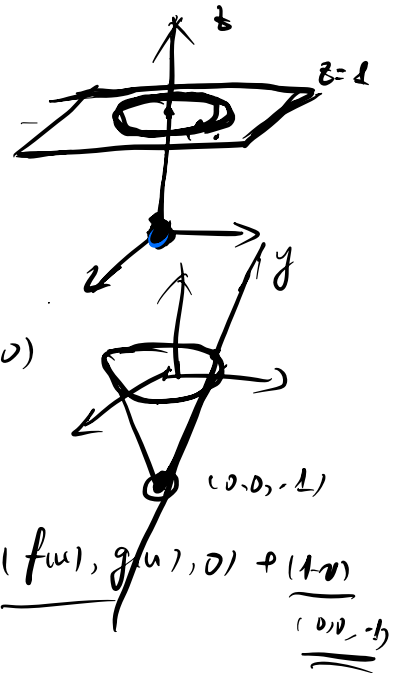
$$a_{(u, v)} = \left(\underbrace{(f(u), g(u))}_{(f(u), g(u), 0)}, \underbrace{(1)}_{(0, 0, 1)} \right)$$

$$a_u = v(f', g', 0)$$

$$a_v = (f, g, 1)$$

$$a_u \times a_v = \begin{vmatrix} i & j & k \\ vf' & vg' & 0 \\ f & g & 1 \end{vmatrix}$$

$$= v(g', -f', f'g - fg')$$



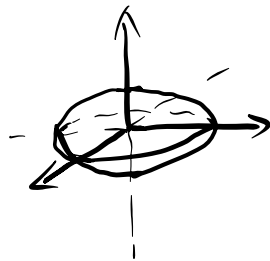
$$\alpha u \times \alpha v \neq 0 \Leftrightarrow v \sqrt{(g')^2 + (f')^2 + (fg - fg')^2} \neq 0.$$

$$\Leftrightarrow v \neq 0 \text{ or } (g')^2 + (f')^2 \neq 0$$

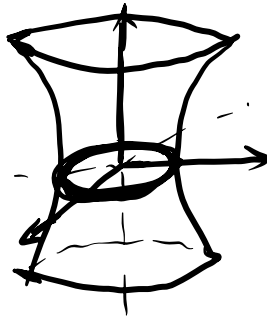
$\gamma'(t) \neq 0$

Exam

(i) ellipsoid : $\frac{x^2}{p^2} + \frac{y^2}{q^2} + \frac{z^2}{r^2} = 1$

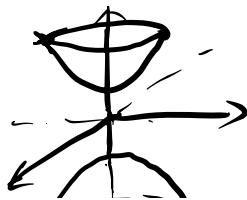


(ii) hyperboloid of one sheet $\frac{x^2}{p^2} + \frac{y^2}{q^2} - \frac{z^2}{r^2} = 1$



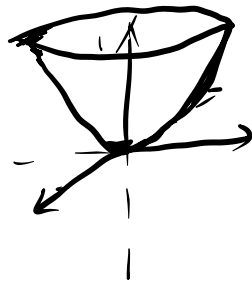
(iii) hyperboloid of two sheets

$$\frac{x^2}{p^2} - \frac{y^2}{q^2} - \frac{z^2}{r^2} = 1$$



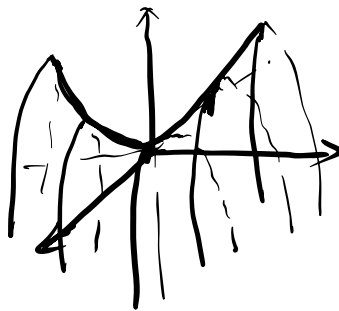
(iv) elliptic paraboloid

$$\frac{x^2}{p^2} + \frac{y^2}{q^2} = z$$



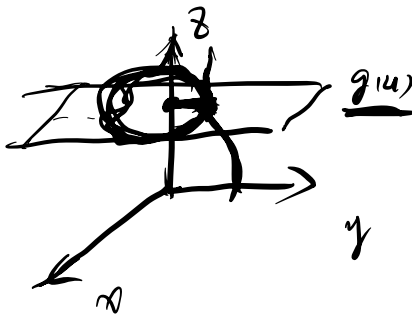
$$\alpha(x,y) = (x, y, x^2y^2)$$

(v) hyperbolic paraboloid $\frac{x^2}{p^2} - \frac{y^2}{q^2} = z$



PC1 - PC3

Exam

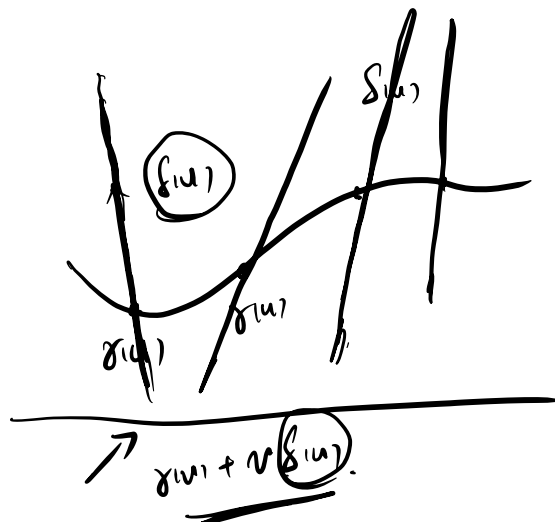


Exercise

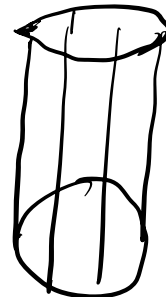
$$\gamma(u) = (0, f(u), g(u))$$

$$\alpha(u,v) = (f(u)\cos v, f(u)\sin v, g(u))$$

Exam



$$\sigma(u, v) = \gamma(u) + v \delta(u)$$



\mathbb{R}^2

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

positive

$\sigma(u, v)$

$g =$

$$\begin{pmatrix} \|\sigma_u\|^2 & \sigma_u \cdot \sigma_v \\ \sigma_u \cdot \sigma_v & \|\sigma_v\|^2 \end{pmatrix}$$