

## §4 The First Fundamental Form

### §5.1 Lengths of curves on surfaces (regular).

S  $\alpha(u, v) \leftarrow$  (smooth, injective).

$$\gamma(t) = \alpha(u(t), v(t))$$

$$s = \int_{t_0}^t \|\dot{\gamma}(z)\| dz$$

$$\dot{\gamma}(t) = \alpha_u \dot{u} + \alpha_v \dot{v}$$



$$s = \int_{t_0}^t \|\alpha_u \dot{u} + \alpha_v \dot{v}\| dt$$

$$= \int_{t_0}^t \left[ (\alpha_u \dot{u} + \alpha_v \dot{v}) \cdot (\alpha_u \dot{u} + \alpha_v \dot{v}) \right]^{\frac{1}{2}} dt$$

$$= \int_{t_0}^t \left[ \|\alpha_u\|^2 \dot{u}^2 + 2\alpha_u \cdot \alpha_v \dot{u} \dot{v} + \|\alpha_v\|^2 \dot{v}^2 \right]^{\frac{1}{2}} dt$$

Let

$$E = \|\alpha_u\|^2 (= \alpha_u \cdot \alpha_u)$$

$$F = \alpha_u \cdot \alpha_v$$

$$G = \alpha_v \cdot \alpha_v$$

$$\dot{u} = \frac{du}{dt}$$

$$\dot{u}^2 dt^2 = (du)^2$$

$$\Rightarrow s = \int_{t_0}^t (E \dot{u}^2 + 2F \dot{u} \dot{v} + G \dot{v}^2) dt$$

$$= \int_{t_0}^t [E du^2 + 2F du dv + G dv^2]$$

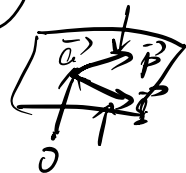
$$\Rightarrow ds^2 = E du^2 + 2F du dv + G dv^2 \leftarrow \text{First fundamental form}$$

$$E = G, F = 0 \quad \text{conformal} \quad (\text{共形})$$

Example 1.1

$$r(u, v) = \vec{a} + u\vec{p} + v\vec{q}, \quad (\vec{p} \cdot \vec{q} = 0)$$

First fundamental form



$$\sigma_u = \vec{p}, \quad \sigma_v = \vec{q} \quad (\vec{p} \cdot \vec{q} = 0?)$$



$$\vec{q} - \vec{p}'$$

$$\vec{p}' = \vec{p} = \frac{\vec{p} \cdot \vec{q}}{|\vec{p}|} \vec{p}$$

$$|\vec{q}| \cos 0 = |\vec{q}| \cdot \frac{\vec{p} \cdot \vec{q}}{|\vec{p}| |\vec{q}|} = \frac{\vec{p} \cdot \vec{q}}{|\vec{p}|}$$

$$\Rightarrow F = \sigma_u \cdot \sigma_v = \vec{p} \cdot \vec{q} = 0$$

$$E = \sigma_u \cdot \sigma_u = |\vec{p}|^2 = 1$$

$$G = \sigma_v \cdot \sigma_v = |\vec{q}|^2 = 1$$

$$\Rightarrow ds^2 = du^2 + dv^2 \quad \text{勾股定理} \quad \mathbb{R}^2$$

Example 4.1.2.  $\sigma(\theta, \varphi) = (\cos\theta \cos\varphi, \cos\theta \sin\varphi, \sin\theta)$

$$\sigma_\theta = (-\sin\theta \cos\varphi, -\sin\theta \sin\varphi, \cos\theta)$$

$$\sigma_\varphi = (-\cos\theta \sin\varphi, \cos\theta \cos\varphi, 0)$$

$$E = \sigma_\theta \cdot \sigma_\theta = 1, \quad F = \sigma_\theta \cdot \sigma_\varphi = 0.$$

$$G = \sigma_\varphi \cdot \sigma_\varphi = \cos^2\theta.$$

$$\Rightarrow ds^2 = \underline{d\theta^2} + \underline{\cos^2\theta d\varphi^2}$$



Example 4.1.3. cylinder

$$\sigma(u, v) = (f(u), g(u), v)$$

$$\underline{f^2 + g^2 = 1}$$

$$\sigma_u = (\underline{f}, \underline{g}, 0), \quad \sigma_v = (\underline{0}, \underline{0}, \underline{1})$$

$$E = \sigma_u \cdot \sigma_u = f^2 + g^2 = 1.$$

$$F = \sigma_u \cdot \sigma_v = 0.$$

$$G = \sigma_v \cdot \sigma_v = 1.$$

$$\Rightarrow \boxed{ds^2 = du^2 + dv^2}$$

Prop 4.1.9. A surface  $\alpha: U \rightarrow \mathbb{R}^3$  is conformal if and only if whenever

$$\underline{\pi_1(t)} = (\underline{u_1(t)}, \underline{v_1(t)}) \quad , \quad \underline{\pi_2(t)} = (\underline{u_2(t)}, \underline{v_2(t)})$$

$$\delta_1(t) = \alpha(\pi_1(t)) \quad , \quad \delta_2(t) = \alpha(\pi_2(t))$$

$$u_1(t_0) = u_2(t_0) = a$$

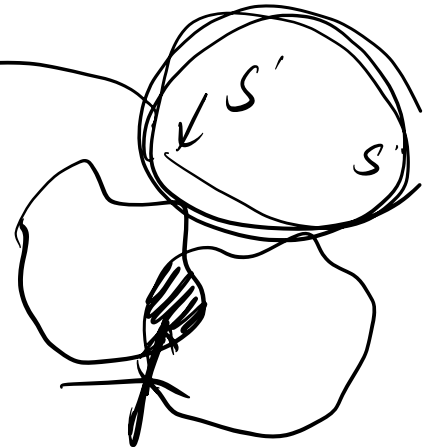
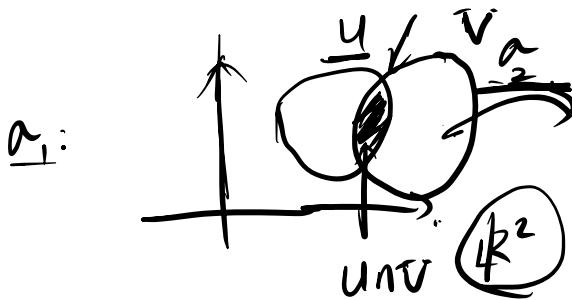
$$v_1(t_0) = v_2(t_0) = b$$

$$\delta_1(t_0) = \delta_2(t_0) = \alpha(a, b)$$

$$\langle \pi_1(t), \pi_2(t) \rangle = \langle \delta_1(t), \delta_2(t) \rangle$$



### § 4.2. Isometries of surfaces.



$$\underline{\Phi}: U \cap V \rightarrow U \cap V \text{ smooth.}$$

$$\underline{\alpha(U \cap V)}$$

$$\Leftrightarrow \underline{\Phi}: \alpha_2^{-1} \circ \alpha_1 \text{ smooth.}$$

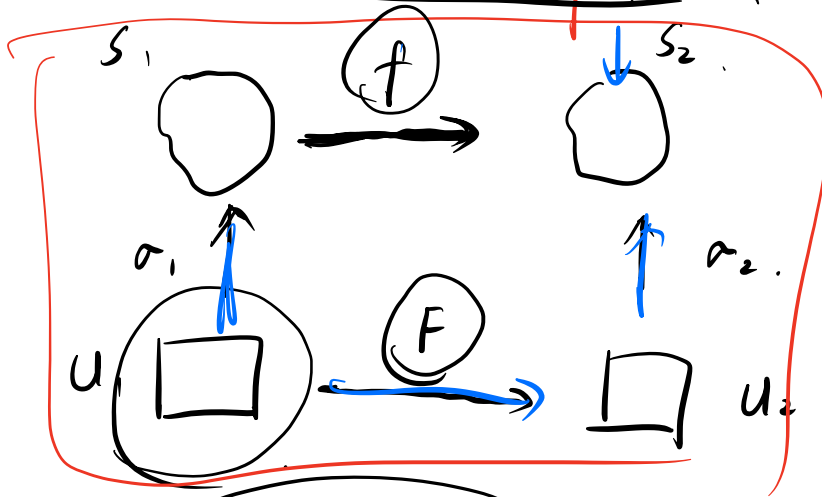
Def Let  $\sigma_1: U_1 \rightarrow \mathbb{R}^3$  and  $\sigma_2: U_2 \rightarrow \mathbb{R}^3$ .  $S_1 = \sigma_1(U_1)$   
 $S_2 = \sigma_2(U_2)$

$f: S_1 \rightarrow S_2$  is said to be smooth if  $\exists F: U_1 \rightarrow U_2$  smooth

st.

$$F = \sigma_2^{-1} \circ f \circ \sigma_1$$

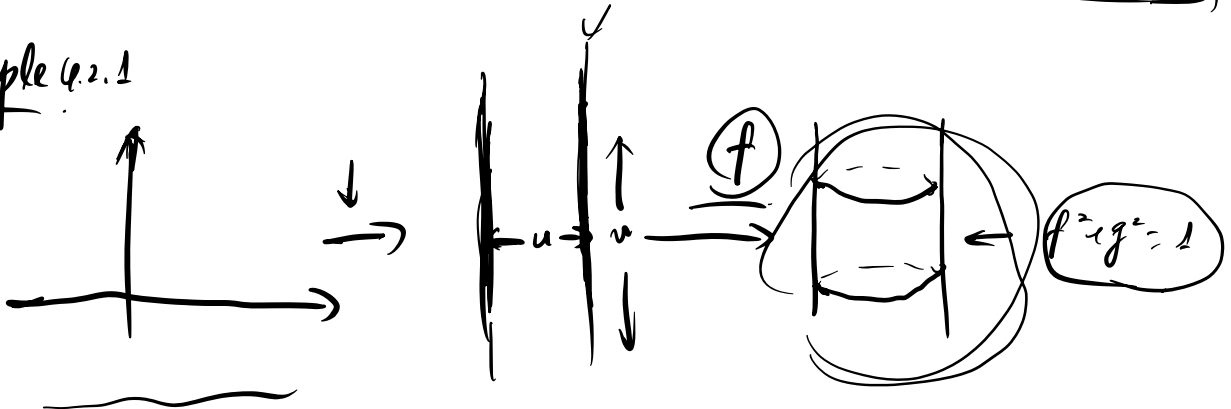
$$f(\sigma_1(u, v)) = \sigma_2(F(u, v))$$



$$f \circ \sigma_1 = \sigma_2 \circ F$$

The  $f: S_1 \rightarrow S_2$  is called a diffeomorphism if  $f$  is bijective and smooth, and  $f^{-1}$  is smooth.

Example 4.2.1





pf. " $\Leftarrow$ "  $S_1 = \sigma_1(u)$ ,  $S_2 = \sigma_2(u)$ .  $ds^2 = E du^2$

Let  $f: S_1 \rightarrow S_2$  be the map such that

$$f(\sigma_1(u, v)) = \sigma_2(u, v).$$

$$f = \sigma_2 \circ \sigma_1^{-1}$$

$$\Rightarrow \begin{cases} f \text{ smooth.} \\ \cancel{f^{-1} \text{ smooth.}} \end{cases}$$

$t \mapsto (u(t), v(t))$ .

$$\begin{cases} \gamma_1(t) = \sigma_1(u(t), v(t)) \in S_1 \\ \gamma_2(t) = \sigma_2(u(t), v(t)) \in S_2 \end{cases}$$

$f$  diffeomorphism

$$f(\gamma_1(t)) = f(\sigma_1(u(t), v(t))) = \sigma_2(u(t), v(t)) = \gamma_2(t).$$

$$\boxed{l(\gamma_1) = \int_{t_0}^t ds = \int_{t_0}^t [E du^2 + 2f du \cdot dv + G dv^2]^{\frac{1}{2}} = l(\gamma_2)}$$

$$\Leftrightarrow \underline{l(\gamma_1) = l(f\gamma_1)}$$

$$\Rightarrow \underline{\tilde{\sigma}_1: U_1 \rightarrow \mathbb{R}^3}, \quad \underline{\tilde{\sigma}_2: U_2 \rightarrow \mathbb{R}^3} \quad S_1 = \tilde{\sigma}_1(U_1), \quad S_2 = \tilde{\sigma}_2(U_2).$$

$$\underline{f: S_1 \rightarrow S_2} \quad \exists \underline{F: U_1 \rightarrow U_2}$$

s.t.

$$\boxed{f \circ \tilde{\sigma}_1 = \tilde{\sigma}_2 \circ F}$$

Let  $\alpha_1 = \tilde{\alpha}_1$ ,  $\alpha_2 = \tilde{\alpha}_2 \circ F$ .

$$\begin{aligned} \rightarrow f(\gamma_1(t)) &= f(\alpha_1(u(t), v(t))) = \tilde{\alpha}_2 \circ f(u(t), v(t)) \\ &= \alpha_2(u(t), v(t)) = \gamma_2(t) \end{aligned}$$

$$\underline{L(\gamma_1(t))} = \underline{L(\gamma_2(t))}.$$

$$\int_{t_0}^t (\bar{E}_1 \dot{u}^2 + 2\bar{F}_1 \dot{u}\dot{v} + \bar{G}_1 \dot{v}^2) dt = \int_{t_0}^t (\bar{E}_2 \dot{u}^2 + 2\bar{F}_2 \dot{u}\dot{v} + \bar{G}_2 \dot{v}^2) dt.$$

$$\Leftrightarrow \bar{E}_1 \dot{u}^2 + 2\bar{F}_1 \dot{u}\dot{v} + \bar{G}_1 \dot{v}^2 = \bar{E}_2 \dot{u}^2 + 2\bar{F}_2 \dot{u}\dot{v} + \bar{G}_2 \dot{v}^2$$

(i)  $u = u_0 + t - t_0$ ,  $v = v_0$ .  $\dot{u} = 1$ ,  $\dot{v} = 0$ .

$$\Rightarrow \bar{E}_1 = \bar{E}_2$$

(ii)  $u = u_0$ ,  $v = v_0 + t - t_0$  —

$$\Rightarrow \bar{G}_1 = \bar{G}_2.$$

(iii)  $u = u_0 + t - t_0$ ,  $v = v_0 + t - t_0 \Rightarrow \dot{u} = 1$ ,  $\dot{v} = 1$

$$\Rightarrow \bar{E}_1 + 2\bar{F}_1 + \bar{G}_1 = \bar{E}_2 + 2\bar{F}_2 + \bar{G}_2.$$

$$\Rightarrow F_1 = F_2.$$



plane:  $ds^2 = du^2 + dv^2$       cylinder:  $ds^2 = du^2 + dv^2$

$\Rightarrow$  plane is isometric to cylinder



tangent developables

$$\alpha(u, v) = \gamma(u) + v \gamma'(u)$$

$(K > 0)$

$$\Rightarrow \alpha_u \times \alpha_v = -\kappa v \mathbf{b} \neq \mathbf{0} \iff \kappa > 0$$

Prop 6.2.4 Any tangent developable is isometric to plane.

pf.  $\alpha(u, v) = \gamma(u) + v \gamma'(u)$

$$\alpha_u = \gamma'(u) + v \gamma''(u), \quad \alpha_v = \gamma'(u)$$

$$\Rightarrow E = 1 + v^2 \kappa^2, \quad F = 1, \quad G = 1$$

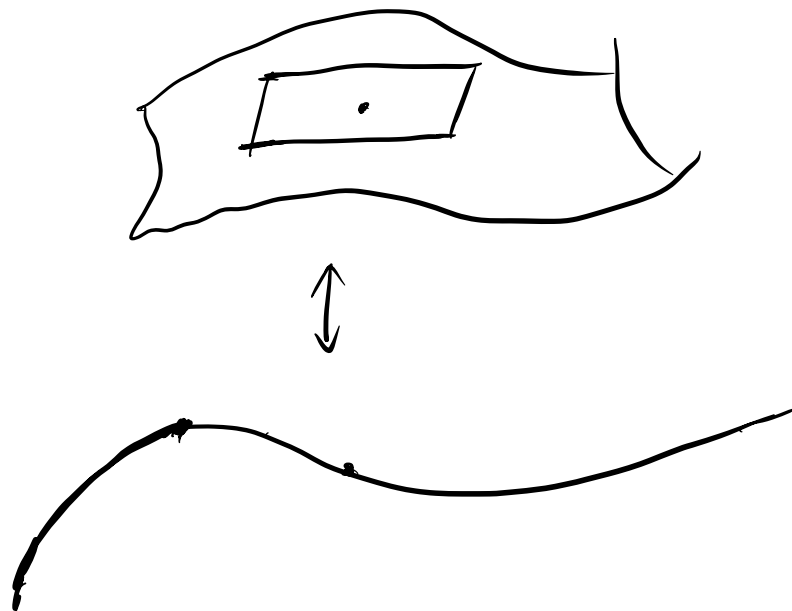
$$\Rightarrow ds^2 = (1 + v^2 \kappa^2) du^2 + 2 du \cdot dv + dv^2$$



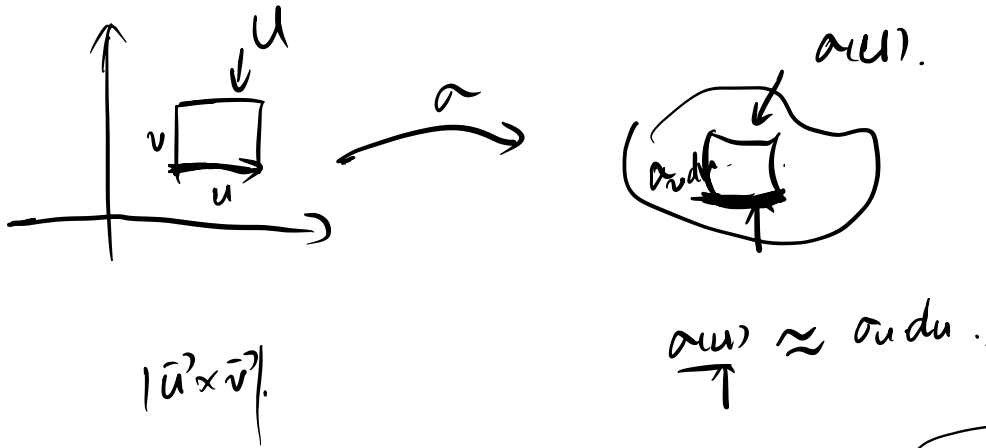
$P: \underline{z(t) + v \dot{z}(t)}$

$\Rightarrow ds^2 = (1 + v^2 k^2) du^2 + 2 du dv + dv^2$

Remark, Any surfaces isometric to plane is plane, a (generalised) cylinder, a (generalised) cone, a tangent developable.



§ 6.3 Surface area.



$$\|\sigma_u du \times \sigma_v dv\| = \|\sigma_u \times \sigma_v\| du dv$$

Def 4.3.1 Let  $\sigma: U \rightarrow \mathbb{R}^3$ .  $A_\sigma(R)$  is the area of the  $\sigma(R)$

$$A_\sigma(R) = \iint_R \|\sigma_u \times \sigma_v\| du dv$$

Prop 4.3.2  $\|\sigma_u \times \sigma_v\| = (EG - F^2)^{\frac{1}{2}}$

Pf.

$$\begin{aligned} \|\sigma_u \times \sigma_v\|^2 &= \|\sigma_u\|^2 \|\sigma_v\|^2 \sin^2 \theta = (1 - \cos^2 \theta) \\ &= \|\sigma_u\|^2 \|\sigma_v\|^2 - \|\sigma_u\|^2 \|\sigma_v\|^2 \cos^2 \theta \\ &= EG - F^2 \end{aligned}$$

$$\Leftrightarrow A_\sigma(R) = \iint_R (EG - F^2)^{\frac{1}{2}} du dv$$