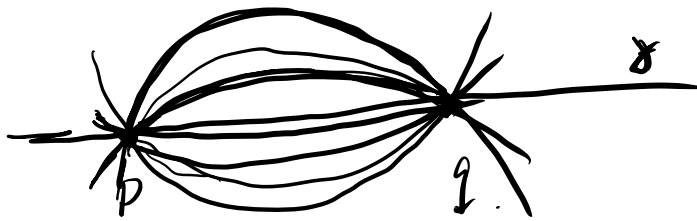


§ 7.2 Geodesics as shortest paths.



$$\gamma_\tau(t) : (-\varepsilon, \varepsilon) \rightarrow S, \quad \tau \in G(-\delta, \delta)$$

$$-\varepsilon < a < b < \varepsilon$$

$$(1) \quad \gamma_\tau(a) = p, \quad \gamma_\tau(b) = q, \quad \forall \tau \in G(-\delta, \delta)$$

$$(2) \quad \gamma : (-\delta, \delta) \times (-\varepsilon, \varepsilon) \rightarrow S$$

$$(\tau, t) \mapsto \gamma_\tau(t), \quad (\text{smooth})$$

$$L(\gamma_\tau) = \int_a^b \|\dot{\gamma}_\tau\| dt$$

$$\tau=0, \quad \gamma_0 = \gamma(t)$$

Thm 7.2.1. The unit speed curve  $\gamma$  is a geodesic if and only

if

$$\frac{d}{d\tau} L(\gamma_\tau) \Big|_{\tau=0} = 0$$

variation

Pf

$$\frac{d}{d\tau} L(\gamma_\tau) = \frac{d}{d\tau} \int_a^b \|\dot{\gamma}_\tau\| dt$$

$$= \int_a^b \frac{\partial}{\partial \tau} \left( \underbrace{g(\tau, t)}_{\text{metric}} (\dot{u}^2 + 2f \dot{u} \dot{v} + G \dot{v}^2) \right)^{\frac{1}{2}} dt$$

$$= \frac{1}{2} \int_a^b g^{-\frac{1}{2}} \left( \frac{\partial g}{\partial c} \right) dt.$$

$$\frac{\partial g}{\partial c} = \frac{\partial E}{\partial c} \dot{u}^2 + 2 \frac{\partial F}{\partial c} \dot{u} \dot{v} + \frac{\partial G}{\partial c} \dot{v}^2 + 2E \dot{u} \frac{\partial \dot{u}}{\partial c} + 2F \left( \frac{\partial \dot{u}}{\partial c} \dot{v} + \dot{u} \frac{\partial \dot{v}}{\partial c} \right) + 2G \dot{v} \frac{\partial \dot{v}}{\partial c}$$

$$= \left( E_u \frac{\partial u}{\partial c} + E_v \frac{\partial v}{\partial c} \right) \dot{u}^2 + 2 \left( F_u \frac{\partial u}{\partial c} + F_v \frac{\partial v}{\partial c} \right) \dot{u} \dot{v} + \left( G_u \frac{\partial u}{\partial c} + G_v \frac{\partial v}{\partial c} \right) \dot{v}^2$$

$$+ 2E \dot{u} \left( \frac{\partial^2 u}{\partial c \partial t} \right) + 2F \left( \frac{\partial^2 u}{\partial c \partial t} \dot{v} + \frac{\partial^2 v}{\partial c \partial t} \dot{u} \right) + 2G \dot{v} \left( \frac{\partial^2 v}{\partial c \partial t} \right)$$

$$\int_a^b g^{-\frac{1}{2}} \left\{ (E \dot{u} + F \dot{v}) \left( \frac{\partial^2 u}{\partial c \partial t} \right) + (F \dot{u} + G \dot{v}) \left( \frac{\partial^2 v}{\partial c \partial t} \right) \right\} dt$$

$$= g^{-\frac{1}{2}} (E \dot{u} + F \dot{v}) \left( \frac{\partial u}{\partial c} \right) + (F \dot{u} + G \dot{v}) \left( \frac{\partial v}{\partial c} \right) \Big|_a^b$$

$$- \int \left( \frac{d}{dt} \left( g^{-\frac{1}{2}} (E \dot{u} + F \dot{v}) \frac{\partial u}{\partial c} + \frac{d}{dt} \left( g^{-\frac{1}{2}} (F \dot{u} + G \dot{v}) \frac{\partial v}{\partial c} \right) \right) dt.$$

$$\delta c(a) = p, \quad \delta c(b) = q.$$

$$\frac{\partial \delta c}{\partial c} \Big|_a \neq 0, \quad \frac{\partial \delta c}{\partial c} \Big|_b = 0$$

$$\Rightarrow \frac{\partial u}{\partial c} \sigma_u + \frac{\partial v}{\partial c} \sigma_v = 0 \Rightarrow$$

$$\left. \begin{aligned} \frac{\partial u}{\partial c} \Big|_a = 0, & \quad \frac{\partial v}{\partial c} \Big|_a = 0 \\ \frac{\partial u}{\partial c} \Big|_b = 0 & \Rightarrow \quad \frac{\partial v}{\partial c} \Big|_b = 0. \end{aligned} \right\}$$

$$\frac{d}{dt} L(\gamma_c) = \int_a^b U \frac{\partial U}{\partial c} + V \frac{\partial V}{\partial c} dt, \quad c=0$$

$$U = \frac{1}{2} g^{-1} (\bar{E}_u \dot{u}^2 + 2f_{ui} \dot{u} \dot{v}^i + G_{uv} \dot{v}^2) - \frac{d}{dt} (g^{-1} (\bar{E} \dot{u} + F \dot{v}))$$

$$V = \frac{1}{2} g^{-1} (\bar{E}_v \dot{v}^2 + 2f_{vi} \dot{v} \dot{u}^i + G_{vu} \dot{u}^2) - \frac{d}{dt} (g^{-1} (F \dot{u} + G \dot{v}))$$

①  $\gamma_0 = \gamma$  unit speed.  $\|g(\dot{\gamma}, \dot{\gamma})\| = 1$

$\Rightarrow$   $\gamma$  is a geodesic

$\Leftarrow$   $\|\dot{\gamma}\| = \text{const}$

$\phi$  (cut-off)

It suffices to show

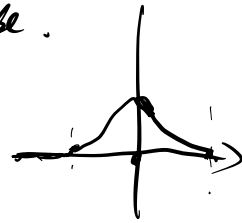
$$\int_a^b U \frac{\partial U}{\partial c} + V \frac{\partial V}{\partial c} dt \Big|_{c=0} = 0 \Rightarrow U=0, V=0 \Big|_{c=0}$$

$\exists$  to  $G(a,b)$  s.t.  $U(0,t_0) > 0$ .  $\exists \eta > 0$ , s.t.  $\forall t \in$   $(t_0 - \eta, t_0 + \eta)$   
 $\uparrow$  continuity

$U(0, t) > 0$ . Let  $\phi(t)$  be a <sup>smooth</sup> function such that

$\phi > 0$  on  $(t_0 - \eta, t_0 + \eta)$ ,  $\phi = 0$ , else.

$$u(x, t) = u(x, t) + \tau \phi(t) \quad v(x, t) = v(x, t)$$



$$\frac{\partial u}{\partial t} = \phi(t)$$

$$\frac{\partial v}{\partial t} = 0$$

$$\Rightarrow \int_a^b u \phi(t) dt = 0, \quad \tau = 0$$

$$\Rightarrow \int_{t_0 - \eta}^{t_0 + \eta} \underbrace{u \phi(t)}_{> 0} dt \stackrel{!}{=} 0, \quad \tau = 0.$$

$> 0$ , contradiction.

$$\Rightarrow \underline{u(0, t) = 0}.$$

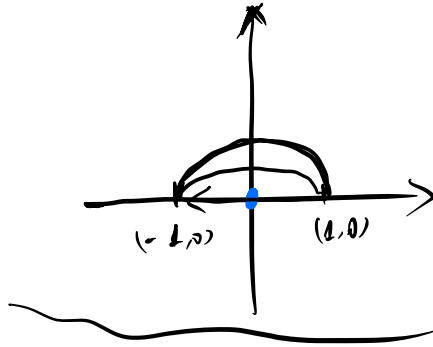
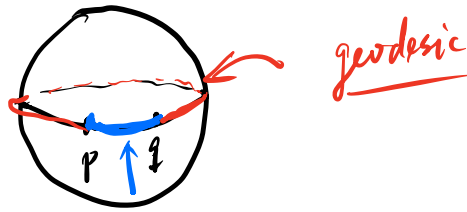
Similarly,  $v(0, t) = 0$ .

}  $\Rightarrow$   $\gamma$  is a geodesic.  $\checkmark$

$$\theta(t) = \begin{cases} e^{-\frac{1}{t^2}}, & t > 0 \\ 0, & t \leq 0 \end{cases} \leftarrow \text{smooth}$$

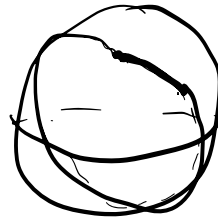
- If  $\gamma$  is shortest path, then  $\gamma$  is a geodesic.

$\nleftarrow$



complete 完备.

•  $\mathbb{R}^3$  closed subset.



§7. Gauss's Theorema Egregium.

§7.1 Gauss's remarkable theorem.

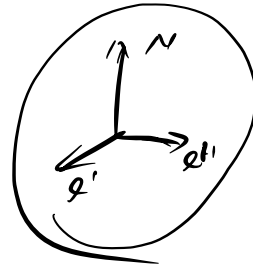
$$K = \underline{k_1 k_2} = \frac{\underline{LN - M^2}}{EG - F^2} \quad \underline{\det II}.$$

Thm 7.1.1. The gaussian curvature of a surface depends only on its first fundamental form, i.e. it is preserved by isometric.

intrinsic

orthonormal basis  $\{e', e''\}$  of  $(T_p S)$   $\leftarrow \{a_u, a_v\}$

$$\begin{cases} e' \cdot e'' = 0 \\ \|e'\| = 1, \|e''\| = 1. \end{cases}$$



$$e'_u = a e' + N$$

$$e'_v = \beta e'' + \mu N$$

$$e''_u = -a' e' + \lambda' N$$

$$e''_v = -\beta' e' + \mu' N$$

$$\boxed{e' \cdot e'' = 0} \Rightarrow a = a', \quad b = b'$$

$$\underline{e'_u = a e' + \lambda' N}$$

$$e'_v = \beta e'' + \mu N$$

$$\underline{e''_u = -a e' + \lambda'' N}$$

$$\underline{e''_v = -\beta e' + \mu'' N}$$

Lemma

$$e'_u \cdot e''_v - e''_u \cdot e'_v = \lambda'' \mu' - \lambda' \mu''$$

$$\begin{aligned}
 &= \alpha_v - \beta_u \\
 &= \frac{LN - M^2}{(\bar{E}G - F^2)^{\frac{1}{2}}} = \underline{K} (\bar{E}G - F^2)^{\frac{1}{2}}
 \end{aligned}$$

pf.  $\alpha_v - \beta_u = \frac{\partial}{\partial u} (e' \cdot e''_v) - \frac{\partial}{\partial v} (e' \cdot e''_u)$

$$\begin{aligned}
 &= e'_u \cdot e''_v + e' \cdot e''_{uv} - e'_v \cdot e''_u - e' \cdot e''_{vu} \\
 &= e'_u e''_v - e'_v e''_u
 \end{aligned}$$

$$N_u \times N_v = \underline{K} \alpha_u \times \alpha_v$$

$$N = \frac{\alpha_u \times \alpha_v}{\|\alpha_u \times \alpha_v\|}, \quad \|\alpha_u \times \alpha_v\| = (\bar{E}G - F^2)^{\frac{1}{2}}$$

$$\Rightarrow \underline{N_u \times N_v} = \frac{LN - M^2}{(\bar{E}G - F^2)^{\frac{1}{2}}} \underline{N}$$

$$\underline{(N_u \times N_v) \cdot N} = \frac{LN - M^2}{(\bar{E}G - F^2)^{\frac{1}{2}}}$$

•  $(a \times b) \cdot (c \times d) = (a \cdot c)(b \cdot d) - (a \cdot d)(b \cdot c)$  (exercise)

a, b, c, d

$$\begin{aligned}
 \Rightarrow (N_u \times N_v) \cdot N &= \underline{(N_u \times N_v) \cdot (e' \times e'')} \\
 &= \underline{(N_u \cdot e')} (N_v \cdot e'') - (N_u \cdot e'') (N_v \cdot e')
 \end{aligned}$$

$$\begin{aligned}
 \bullet \quad \underline{N \cdot e' = 0} &\Rightarrow \underline{N_u \cdot e'} + N \cdot \underline{e'_u} = 0 \\
 &= (N \cdot \underline{e'_u}) \cdot (N \cdot e''_u) - (N \cdot e''_u) (N \cdot e'_u) \\
 &= \underline{\lambda' \mu'' - \lambda'' \mu'}
 \end{aligned}$$

pf of Th 7.1.1. Note that

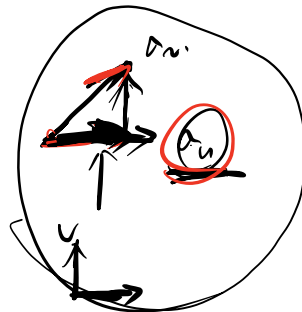
$$k = \frac{\alpha v - \beta u}{(\epsilon u - \rho^2)^{\frac{1}{2}}}$$

$\{a_u, a_v\}$  is a basis of TPS.

Cram-Schmidt process

$$\underline{e'} = \frac{a_u}{\|a_u\|} = \underline{\epsilon a_u}$$

$$\underline{v} = \frac{a_v}{\|a_v\|}$$



$$\underline{e''} = \underline{\delta a_u + \gamma a_v}$$

$$\underline{e' \cdot e'' = 0, \|e''\| = 1}$$

$$\Rightarrow \left\{ \begin{array}{l} \epsilon^{-\frac{1}{2}} (\delta \epsilon + \gamma \rho) = 0 \end{array} \right.$$

$$\delta^2 \epsilon + 2\delta \gamma \rho + \gamma^2 \rho^2 = 1$$

$\Rightarrow$





$$\left\{ \begin{array}{l} \gamma = \frac{FE^{-\frac{1}{2}}}{(EG-f^2)^{\frac{1}{2}}} \\ \delta = \frac{E^{\frac{1}{2}}}{(EG-f^2)^{\frac{1}{2}}} \end{array} \right., \quad \underline{e = E^{-\frac{1}{2}}}$$

•  $e' = e a_u$ ,  $e'' = \gamma a_u + \delta a_v$ .

$\alpha = e'u \cdot e''$

$$= (e u a_u + e a_{uu}) \cdot (\gamma a_u + \delta a_v)$$

$$= \frac{eu}{e} \cancel{e' \cdot e''} + e \gamma \underbrace{a_{uu} \cdot a_u} + e \delta \underbrace{a_{uu} \cdot a_v}$$

$$= \frac{1}{2} e \gamma \underbrace{(a_u \cdot a_u)_u} + e \delta \left( \underbrace{(a_u \cdot a_v)_u} - \frac{1}{2} \underbrace{(a_u \cdot a_u)_v} \right)$$

$$= \underline{\underline{\frac{1}{2} e \gamma E_u + e \delta (f_u - \frac{1}{2} E_v)}}$$

$\beta = e'v \cdot e''$

$$= (e v a_u + e a_{uv}) \cdot (\gamma a_u + \delta a_v)$$

$$= \frac{ev}{e} \cancel{e' \cdot e''} + e \gamma \underbrace{a_{uv} \cdot a_u}_{\frac{1}{2} (a_u \cdot a_u)_v} + e \delta \underbrace{a_{uv} \cdot a_v}_{\frac{1}{2} (a_v \cdot a_v)_u}$$

$$= \underline{\underline{\frac{1}{2} (e \gamma) E_v + \frac{1}{2} e \delta G_v}}$$

$$k = \frac{\alpha v - \beta u}{(\epsilon G - F^2)^{\frac{1}{2}}} \quad \checkmark$$

•  $\underline{k \sim I}$

Cor 7.1.3

$$k = \frac{1}{(\epsilon G - F^2)^{\frac{1}{2}}} \left\{ \begin{array}{l} -\frac{1}{2} \bar{E}_{vv} + F_{uv} - \frac{1}{2} G_{uu} \quad \frac{1}{2} \bar{E}_u \quad F_u - \frac{1}{2} \bar{E}_v \\ F_v - \frac{1}{2} G_u \\ \frac{1}{2} G_v \end{array} \right\}$$

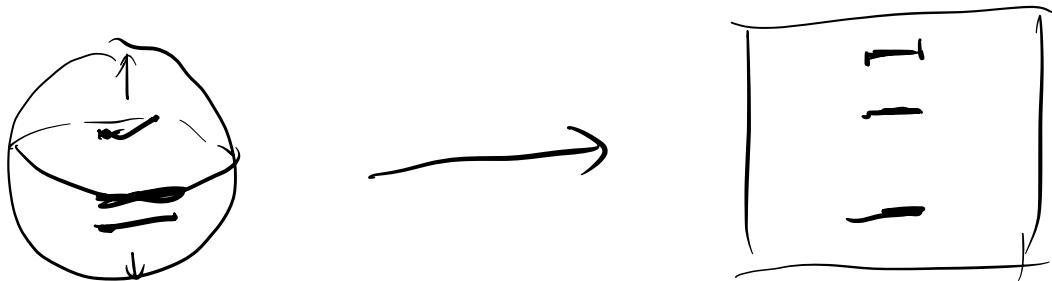
$$- \left\{ \begin{array}{l} 0 \quad \frac{1}{2} \bar{E}_v \quad \frac{1}{2} G_u \\ \frac{1}{2} \bar{E}_v \quad E \quad F \\ \frac{1}{2} G_u \quad F \quad G \end{array} \right\}$$

Cor (a)  $F=0$

$$k = - \frac{1}{2\sqrt{\epsilon G}} \left\{ \frac{\partial}{\partial u} \left( \frac{G_u}{\sqrt{\epsilon G}} \right) + \frac{\partial}{\partial v} \left( \frac{\bar{E}_v}{\sqrt{\epsilon G}} \right) \right\}$$

(b)  $E=1, F=0$ .

$$k = - G^{-\frac{1}{2}} \frac{\partial^2}{\partial u^2} (G^{\frac{1}{2}})$$



Prop. Any map of any region of the earth's surface must distort distances.

Pf.  $f: S^2 \rightarrow \mathbb{R}^2$   
 $r \mapsto kr.$

$f \circ k^{-1}: S^2 \rightarrow \mathbb{R}^2$   
 $k \mapsto r.$

$K(S^2) = K(\mathbb{R}^2)$  X.

$K(S^2) = \frac{1}{R^2}$  ,  $K(\mathbb{R}^2) = 0.$

Prop. (Gauss equation) Qu. 11

$$\left\{ \begin{aligned} \sigma_{uu} &= \Gamma_{11}^1 \sigma_u + \Gamma_{11}^2 \sigma_v + L \vec{N} \\ \sigma_{uv} &= \Gamma_{12}^1 \sigma_u + \Gamma_{12}^2 \sigma_v + M \vec{N} \\ \sigma_{vv} &= \Gamma_{22}^1 \sigma_u + \Gamma_{22}^2 \sigma_v + N \vec{N} \end{aligned} \right.$$

$$\Gamma_{11}^1 = \frac{G\bar{E}_u - 2F\bar{E}_u + F\bar{E}_v}{2(EG - F^2)}, \quad \Gamma_{11}^2 = \frac{2E\bar{F}_u - E\bar{E}_v - F\bar{E}_u}{2(EG - F^2)}$$

$$\Gamma_{12}^1 = \frac{G\bar{E}_v - F\bar{G}_u}{2(EG - F^2)}, \quad \Gamma_{12}^2 = \frac{E\bar{G}_u - F\bar{E}_v}{2(EG - F^2)}$$

$$\Gamma_{22}^1 = \frac{2G\bar{F}_v - G\bar{G}_u - F\bar{G}_u}{2(EG - F^2)}, \quad \Gamma_{22}^2 = \frac{E\bar{G}_v - 2F\bar{F}_v + F\bar{G}_u}{2(EG - F^2)}$$

Pf.

$$\left\{ \begin{aligned} \sigma_{uu} &= \alpha_1 \sigma_u + \alpha_2 \sigma_v + \alpha_3 \vec{N} \\ \sigma_{uv} &= \beta_1 \sigma_u + \beta_2 \sigma_v + \beta_3 \vec{N} \\ \sigma_{vv} &= \gamma_1 \sigma_u + \gamma_2 \sigma_v + \gamma_3 \vec{N} \end{aligned} \right.$$

$$\bullet \quad \sigma_{uu} \cdot \vec{N} = \alpha_3 \Rightarrow \alpha_3 = L$$

$$\sigma_{uv} \cdot \vec{N} = \beta_3 \Rightarrow \beta_3 = M$$

$$\sigma_{vv} \cdot \vec{N} = \gamma_3 \Rightarrow \gamma_3 = N$$

$$\bullet \quad \sigma_{uu} \cdot \sigma_u = \alpha_1 E + \alpha_2 F = \frac{1}{2} (\sigma_u \cdot \sigma_u) = \frac{1}{2} \bar{E}_u$$

$$\sigma_{uu} \cdot \sigma_v = \alpha_1 F + \alpha_2 G = F_u - \frac{1}{2} \bar{E}_v$$

$$\Gamma_{11}^1 = \alpha_1, \quad \Gamma_{11}^2 = \alpha_2$$

$$\bullet \quad \underline{\sigma_{uv} \cdot \sigma_u} = \beta_1 \bar{E} + \beta_2 F = \frac{1}{2} \bar{E}_v$$

$$\underline{\sigma_{uv} \cdot \sigma_v} = \beta_1 F + \beta_2 G = \frac{1}{2} \underline{G_u}$$

$$\underline{\Gamma_{12}^1} = \beta_1, \quad \underline{\Gamma_{12}^2} = \beta_2$$



$$1 \leq i, j, k \leq 2$$

Six

Christoffel symbols

$$\bullet \quad g_{11} = \bar{E}, \quad g_{12} = g_{21} = F, \quad g_{22} = G.$$

$$G_1 = \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix}$$

$$\begin{pmatrix} g^{11} & g^{12} \\ g^{21} & g^{22} \end{pmatrix} = G_1^{-1}$$

$$\underline{\Gamma_{ij}^k} = \frac{1}{2} g^{kl} (\underline{\partial_i g_{jl}} + \underline{\partial_j g_{il}} - \underline{\partial_l g_{ij}})$$

Riemannian geometry

Prop (Codazzi - Mainard equation)  $\sigma_{u,v}$   $\Gamma_{ij}^k$

$$\left\{ \begin{array}{l} L v - M u = L P'_{12} + M (P''_{12} - P'_{11}) - N P''_{11} \\ M v - N u = L P'_{22} + M (P''_{22} - P'_{12}) - N P''_{12} \end{array} \right.$$


---

• constant Gaussian curvature

• plane  $K=0$  space form

sphere  $K=1$

• Every compact surface whose gaussian curvature is constant is sphere.   
 ↑ closed, bounded closed subset of  $\mathbb{R}^3$

open set



$B_R = \{ (x,y) : x^2 + y^2 \leq 1 \}$  closed

Poincaré disc  $K=-1$

